

**AMENDMENTS TO THE SPECIFICATION**

Please replace original paragraph 10 with the following amended paragraph:

**[0010]** According to one aspect of the invention an apparatus for moving welded frameworks each having four corners, such as window frames or sashes, from a welding machine to a workstation for further processing of the frameworks includes a track adapted for mounting at an elevated position so as to extend substantially horizontally from the welding machine to the workstation. There is also an arm assembly mounted for movement along the track and having gripping devices arranged one above the other and below the track during use of the apparatus, each gripping device adapted to releasably engage and grip a respective one of the welded frameworks. The apparatus further includes an actuator arrangement for moving the arm assembly along the track between a first position where the arm assembly can engage the frameworks when they are arranged one above the other in the welding machine and then move the framework to a second position where the gripping devices engage and grip the frameworks at the work station during use of the apparatus.

Please replace original paragraph 39 with the following amended paragraph:

**[0039]** Turning now to the apparatus of the invention for moving the window frames, located adjacent to the welding machine 10 is a robot arm assembly indicated generally at 30. In the preferred, complete apparatus for transferring two frameworks from the welding machine, there are two of these robot arm assemblies which are spaced apart on either side of the apparatus, each being mounted on an overhead beam or track 32. Preferably this track 32 is supported on the corner cleaning machine by support posts. The preferred arm assembly on each side of the apparatus includes a lead arm 31 and a gripping assembly arm 34, these being shown on a larger scale and in more detail in Figure 6. The lead arm 31 and the gripping assembly arm 34 are connected together as one arm assembly or unit. Each gripping assembly arm has two grippers or gripping devices 35 arranged one above the other and below their respective track 32. These gripping devices are positioned at the lower end of

their respective arm 34 and are connected to selectively clamp the window frames. In other words, the gripping devices are shaped and designed to grip the two welded frameworks 12, 14 and releasably clamp them in place in a desired position for processing either by the corner cleaner as will be described below or by a different form of workstation capable of carrying out additional manufacturing steps after the welding operation. It will be understood that the preferred grippers 35 each have two recesses which allow for gripping of the framework from either the left or the right side. Each of the lead arms and gripping assembly arms are movable vertically to allow the gripping assembly arm 34 and the lead arm 31 to pass over the frameworks 12, 14 during processing as will be discussed below.